LÉVY PROCESSES IN SEMISIMPLE LIE GROUPS AND STABILITY OF STOCHASTIC FLOWS

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ABSTRACT. We study the asymptotic stability of stochastic flows on compact spaces induced by Levy processes in semisimple Lie groups. It is shown that the Lyapunov exponents can be determined naturally in terms of root structure of the Lie group and there is an open subset whose complement has a positive codimension such that, after a random rotation, each of its connected components is shrunk to a single moving point exponentially under the flow.

1. Introduction

In this paper, we are concerned with the asymptotic stability of the stochastic flows induced by Lévy processes in noncompact semisimple Lie groups.

Although the class of such stochastic flows is rather narrow, it includes many interesting examples. For example, let S^{n-1} be the unit sphere in R^n and let Y_i be the orthogonal projection to S^{n-1} of the coordinate vector field $\partial/\partial x_i$ on R^n . Consider the following SDE (stochastic differential equation) on S^{n-1} :

(1)
$$dx_t = \sum_{i=1}^n c_i Y_i(x_t) \circ dw_t^i,$$

where the c_i 's are arbitrary constants, $w_t = (w_t^1, \dots, w_t^n)$ is an *n*-dimensional Wiener process and $\circ d$ denotes the Stratonovich differential. The solution flow of this SDE can be regarded as a Lévy process in the connected Lorentz group $SO_+(1,n)$. When all $c_i = 1$, the stochastic flow is called the gradient flow and has been studied by Baxendale [2] and Elworthy [4].

The above example has the following physical interpretation. Imagine S^{n-1} is the surface of a globe, fixed at its center, on which particles are distributed. Assume the particles can move freely along the surface. The above stochastic flow describes the motion of these particles under the influence of a random air flow. We may also assume that the globe is subject to random rotations, either continuously or at randomly spaced intervals, to obtain a stochastic flow induced by a more general Lévy process in $SO_{+}(1,n)$.

We will see that the asymptotic properties of the stochastic flows, at least qualitatively, are completely determined by the structure of the group in which they lie. As for the above example with $SO_+(1,n)$, it will be shown that almost surely, there is a random point in S^{n-1} such that all the particles off this point will be swept to a single "moving" point exponentially fast by the stochastic flow.

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In [9, 10, 11], we considered the stochastic flows induced by a special type of Lévy processes, i.e., the horizontal diffusions, in noncompact semisimple Lie groups. Using the limiting properties of horizontal diffusions found in Malliavin and Malliavin [12], we were able to prove some very explicit results on the asymptotic stability of the stochastic flows, which include the results on gradient flows on spheres as special cases. However, as the horizontal diffusions are rather special, the applications of these results were limited. For example, they do not cover stochastic flows generated by the SDE (1) when the constants c_i are not equal.

In this paper, we will apply the results found in Guivarc'h and Raugi [5] on the limiting properties of random walks on noncompact semisimple Lie groups, which extend some earlier results by Furstenberg and others (see the references in [5]). By adapting these results for Lévy processes, we will be able to treat the asymptotic stability of stochastic flows much more general than those considered in [9, 10, 11].

After a brief introduction to semisimple Lie groups in Section 2 and Lévy processes in Lie groups in Section 3, we will state a basic result on the limiting properties of Lévy processes in Section 4. The discrete time version of this result is given in [5]. Although the corresponding result for Lévy processes does not follow directly from this, it can be proved by essentially the same arguments of [5]. We also discuss some sufficient conditions for the desired limiting properties to hold.

In Section 5, we will obtain an integral formula for the rates at which the Lévy process tends to infinity. These rates determine the Lyapunov exponents of the stochastic flows to be discussed later. Our formula is more explicit than the one obtained in [5], and may lead to explicit calculation of the rates in some special cases.

Our main results on the asymptotic stability of the stochastic flows induced by Lévy processes are contained in Sections 6, 7 and 8. Let G be a noncompact semisimple Lie group and let Q be a closed subgroup. A Lévy process g_t in G can be naturally regarded as a stochastic flow on the left coset space $Q \setminus G$ via the right action of G. Although it is perhaps more customary to work with the left action, the use of the right action for stochastic flows is natural because the Lévy processes defined here are left invariant, which is consistent with most literature on this subject.

The local stability of the stochastic flow is determined by its Lyapunov exponents, which give the exponential rates at which the distance between near points grows or decays. We will see that all the Lyapunov exponents, together with the associated filtration of the tangent space, can be expressed using the roots of G. We will also obtain the global structure of stability, namely, we will show that there exist an open subset Λ of $Q\backslash G$ whose complement has a positive codimension, and a random "rotation" k_{ω} , such that almost surely, each connected component of $k_{\omega}(\Lambda)$ is shrunk to a single point exponentially fast under the flow. The set Λ has a natural structure and, in concrete examples, can be determined explicitly. The random open set $k_{\omega}(\Lambda)$ is the stable manifold of the stochastic flow mentioned in [3]. It is worth noting that the set Λ is completely determined by the group G and is independent of the process g_t . Our results substantially extend the results obtained previously. Section 7 contains several technical lemmas used in proving the result for Lyapunov exponents. The approach is different from the one given in [9], which works only for horizontal diffusions.

In the last section, we will apply our theory to study several stochastic flows on spheres induced by Lévy processes in SL(n,R) and $SO_{+}(1,n)$.

2. Some Preliminaries

Throughout, we will assume that G is a semisimple Lie group of noncompact type with a finite center. The reader is referred to [6] for the general theory of semisimple Lie groups. A typical example is given by G = SL(n, R), the group of n by n real matrices of determinant one.

Let K be a maximal compact subgroup of G. We will always use capital Roman letters for Lie groups and the corresponding script letters for their Lie algebras. Hence, \mathcal{G} and \mathcal{K} will be respectively the Lie algebras of G and K.

Any $X \in \mathcal{G}$ is a tangent vector of G at the identity element e of G. For any $g \in G$, we will let gX and Xg be respectively the vectors at g obtained by left and right translations. For matrix groups, this notation coincides with the matrix multiplication.

The Killing form B of \mathcal{G} is defined by $B(X,Y)=\operatorname{Trace}[ad(X)ad(Y)]$, for $X,Y\in\mathcal{G}$, where $ad(X)\colon\mathcal{G}\to\mathcal{G}$ is defined by ad(X)Y=[X,Y] (Lie bracket). The Lie group G being semisimple means that B is nondegenerate. Let \mathcal{P} be the orthogonal complement of \mathcal{K} in \mathcal{G} with respect to B. It is Ad(K)-invariant in the sense that $Ad(k)Y\in\mathcal{P}$ for any $Y\in\mathcal{P}$ and $k\in K$, where $Ad(k)Y=kYk^{-1}$. The Killing form B is positive definite when restricted to \mathcal{P} and negative definite when restricted to \mathcal{K} . It induces an Ad(K)-invariant inner product $\langle\cdot,\cdot\rangle$ on \mathcal{G} by setting it equal to B on \mathcal{P} , -B on \mathcal{K} and keeping the orthogonality of \mathcal{P} and \mathcal{K} .

Let \mathcal{A} be a maximal abelian subspace of \mathcal{P} . A nonzero linear functional α on \mathcal{A} is called a root if the vector space

$$\mathcal{G}_{\alpha} = \{ X \in \mathcal{G}; \ ad(H)X = \alpha(H)X \text{ for } H \in \mathcal{A} \}$$

is nontrivial. The space \mathcal{G}_{α} is called the root space, any $X \in \mathcal{G}_{\alpha}$ a root vector, and $\dim(\mathcal{G}_{\alpha})$ the multiplicity of α . We have $\mathcal{G} = \mathcal{G}_0 \oplus \sum_{\alpha} \mathcal{G}_{\alpha}$ as an orthogonal decomposition with respect to $\langle \cdot, \cdot \rangle$. Let A be the connected abelian subgroup of G with \mathcal{A} as Lie algebra.

The hyperplanes $\alpha=0$ divide \mathcal{A} into several open convex cones called Weyl chambers. Fix a Weyl chamber \mathcal{A}_+ . A root α is said to be positive (relative to \mathcal{A}_+) if $\alpha>0$ on \mathcal{A}_+ . If a root is not positive, then it is $-\alpha$ for some positive root α and will be called a negative root.

Since $[\mathcal{G}_{\alpha}, \mathcal{G}_{\beta}] \subset \mathcal{G}_{\alpha+\beta}$ $(\mathcal{G}_{\alpha+\beta} = \{0\} \text{ if } \alpha+\beta \text{ is not a root or zero}), \mathcal{N} = \sum_{\alpha>0} \mathcal{G}_{-\alpha}$ and $\mathcal{N}^+ = \sum_{\alpha>0} \mathcal{G}_{\alpha}$ are both Lie subalgebras of \mathcal{G} , where the summations are taken over all positive roots. Let N and N^+ be respectively the connected Lie subgroups of G with \mathcal{N} and \mathcal{N}^+ as Lie algebras. Both are nilpotent groups. We have the following two versions of Iwasawa decompositions:

$$(2) G = NAK = N^+AK,$$

in the sense that the maps $(n, a, k) \mapsto g = nak$ and $(n', a, k) \mapsto g = n'ak$ are, respectively, diffeomorphisms from $N \times A \times K$ and $N^+ \times A \times K$ onto G.

Any $g \in G$ can be written as $g = x \exp(H^+)y$ for some $x, y \in K$ and a unique $H^+ \in \overline{\mathcal{A}_+}$, the closure of \mathcal{A}_+ . This is called the Cartan decomposition. Although the choice for (x, y) is not unique, when $H^+ \in \mathcal{A}_+$, all the possible choices are given by $(xm, m^{-1}y)$ for $m \in M$, where M is the centralizer of A in K, i.e., $M = \{k \in K; kak^{-1} = a \text{ for } a \in A\}$.

For G = SL(n, R), \mathcal{G} is sl(n, R), the space of n by n real matrices of trace zero with [X, Y] = XY - YX, $B(X, Y) = 2n \operatorname{Trace}(XY)$ and $\langle X, Y \rangle = 2n \operatorname{Trace}(XY^*)$, where Y^* is the transpose of Y. One may take K to be SO(n), the subgroup

of orthogonal matrices, whose Lie algebra \mathcal{K} is the space o(n) of skew-symmetric matrices. Then \mathcal{P} is the space of symmetric matrices of trace zero. One may take $\mathcal{A} = \{ \operatorname{diag}(a_1, a_2, \cdots, a_n); \sum_i a_i = 0 \}$ and $\mathcal{A}_+ = \{ \operatorname{diag}(a_1, a_2, \cdots, a_n) \in \mathcal{A}; a_1 > a_2 > \cdots > a_n \}$. The roots are α_{ij} , defined by $\alpha_{ij}(H) = a_i - a_j$ for $H = \operatorname{diag}\{a_1, a_2, \ldots, a_n\}$. The corresponding root space is 1-dimensional and is spanned by E_{ij} , the matrix which has 1 at place (i, j) and 0 elsewhere. The positive roots are given by α_{ij} with i < j. We have $A = \{\operatorname{diag}(a_1, a_2, \cdots, a_n); a_i > 0 \text{ and } \prod_i a_i = 1\}$; M is the group of the diagonal matrices with ± 1 as diagonal entries and with an even number of -1's; and N and N^+ are, respectively, the groups of lower triangular matrices and upper triangular matrices with diagonal entries all equal to one.

Let $B = G/(N^+AM)$ and let $\pi \colon G \to B$ be the natural projection. Via the Iwasawa decomposition $G = N^+AK$, B can be naturally identified with K/M. We note that B is a left G-space in the sense that any $g \in G$ acts on B on the left by sending $g'(N^+AM)$ into $gg'(N^+AM)$. Similarly, let \tilde{B} be the left coset space $(NAM)\backslash G$ and let $\tilde{\pi} \colon G \to \tilde{B}$ be the natural projection. Via the Iwasawa decomposition G = NAK, \tilde{B} can be identified with $M\backslash K$. We note that \tilde{B} is a right G-space in the sense that any $g \in G$ acts on \tilde{B} on the right by sending (NAM)g' into (NAM)g'g.

Besides the Iwasawa and Cartan decompositions, there is a third very useful decomposition on G, called the Bruhat decomposition. Let M' be the normalizer of A in K, i.e., $M' = \{k \in K; kAk^{-1} \subset A\}$. Then M is a normal subgoup of M', and W = M'/M is a finite group called the Weyl group. Any $w \in W$ can be considered as a linear transformation on A, defined by $w(H) = Ad(m_w)H$, for $H \in A$, where $m_w \in M'$ represents $w \in W = M'/M$. We have the following Bruhat decomposition:

(3)
$$G = \bigcup_{w \in W} N m_w N^+ A M = \bigcup_{w \in W} N A M m_w N^+ \quad \text{(disjoint unions)},$$

where both NN^+AM and $NAMN^+$ are open subsets of G whose complements have positive codimensions. It follows that $\pi(N)$ and $\tilde{\pi}(N^+)$ are, respectively, connected open subsets of B and \tilde{B} with positive-codimensional complements.

3. Lévy Processes

A Lévy process g_t in G is a Markov process whose transition semigroup P_t is given by $P_t f(g) = \int_G f(g\sigma) \mu_t(d\sigma)$, where $\{\mu_t\}$ is a family of probability measures on G satisfying $\mu_t * \mu_s = \mu_{t+s}$ and μ_t converges weakly to δ_e , the point mass at the identity element e of G, as $t \to 0$. The convolution $\mu_t * \mu_s$ is defined by $\mu_t * \mu_s(\Gamma) = \int_{ab \in \Gamma} \mu_t(da) \mu_s(db)$. By taking a proper version, we may assume that g_t has right continuous paths with left limits.

Our Lévy process is left invariant in the sense that for any $g \in G$, gg_t is the same Markov process starting at gg_0 . A right invariant Lévy process is obtained with semigroup $P_t f(g) = \int_G f(\sigma g) \mu_t(d\sigma)$.

Let X_1, X_2, \ldots, X_m be a basis of \mathcal{G} which is orthonormal with respect to the inner product $\langle \cdot, \cdot \rangle$ introduced in Section 2. Any $X \in \mathcal{G}$ can be identified with the left invariant vector field gX, for $g \in G$. There are smooth functions x_1, x_2, \ldots, x_m on G such that $x_i(e) = 0$, $\lim_{g \to \infty} x_i(g)$ exist and $X_i x_j(e) = \delta_{ij}$. In a neighborhood of e, x_i can be defined by $g = \exp(\sum_i x_i(g)X_i)$. By [7], a Lévy process g_t in G can

be characterized as a Markov process with generator given by

(4)
$$Lf(g) = \frac{1}{2} \sum_{i,j=1}^{m} a_{ij} X_i X_j f(g) + \sum_{i=1}^{m} b_i X_i f(g) + \int_G [f(g\tau) - f(g) - \sum_{i=1}^{m} x_i(\tau) X_i f(g)] \eta(d\tau),$$

for any smooth function f on G with compact support, where a_{ij} and b_i are constants with a_{ij} forming a symmetric nonnegative definite matrix, and η is a measure on G satisfying $\eta(\{e\}) = 0$, $\int_U \sum_{i=1}^m x_i^2 d\eta < \infty$ and $\eta(G - U) < \infty$ for some compact neighborhood U of e. We note that a_{ij} and η are independent of, but b_i may depend on, the choice of x_i . The measure η is called the Lévy measure of g_t . The process g_t is continuous if and only if $\eta = 0$.

Let $g_t = n_t a_t k_t$ be the Iwasawa decomposition G = NAK. Then k_t is a Markov process in K. To see this, note that if V is a right G-space, then vg_t is a Markov process in V for any $v \in V$, due to the left invariance of g_t . Applying this observation to the right G-space $(NA)\backslash G \equiv K$, we see that $k_t = (NA)g_t$ is a Markov process.

If the Lévy measure η is finite, then the generator (4) can be written as

$$Lf(g) = \frac{1}{2} \sum_{i,j=1}^{m} a_{ij} X_i X_j f(g) + \sum_{i=1}^{m} b_i X_i f(g) + \int_G [f(g\sigma) - f(g)] \eta(d\sigma)$$

$$= (1/2) \sum_{i=1}^{n} U_i U_i f(g) + U_0 f(g) + \int_G [f(g\sigma) - f(g)] \eta(d\sigma),$$
(5)

where $U_1, U_2, \ldots, U_n \in \mathcal{G}$ are chosen to satisfy $\sum_{i=1}^n U_i U_i = \sum_{i,j=1}^m a_{ij} X_i X_j$ and $U_0 = \sum_{i=1}^m b_i X_i$. We note that n is not necessarily equal to m, and the b_i here are different from those in (4).

Applebaum and Kunita [1] obtained the stochastic integral equations satisfied by a general Lévy process. If the Lévy measure η is finite, the equation takes the following simpler form:

$$f(g_t) = f(g_0) + \int_0^t \sum_{i=1}^n U_i f(g_{s-}) \circ dw_s^i + \int_0^t U_0 f(g_s) ds$$

$$+ \int_0^t [f(g_{s-}\sigma) - f(g_{s-})] N(ds d\sigma),$$
(6)

for any smooth function f on G with compact support, where $w_t = (w_t^1, \ldots, w_t^n)$ is an n-dimensional Wiener process and $N(dtd\sigma)$ is a Poisson point process on $[0, \infty) \times G$ with intensity measure given by $dt\eta(d\sigma)$. See, e.g., Section I.9 in [8] for the definition of Poisson point processes. We have, for any nonnegative measurable function f(t, q) on $[0, \infty) \times G$,

$$E[\int_0^t \int_G f(s,g)N(dsdg)] = \int_0^t \int_G f(s,g)\eta(dg)ds.$$

Given $U_0, U_1, \ldots, U_n \in \mathcal{G}$ and a finite measure η on G, the Lévy process g_t given by (6) can be constructed explicitly as follows. Let $w_t = (w_t^1, \ldots, w_t^n)$ be an n-dimensional Wiener process, let S_i be a sequence of exponential random variables with a common mean $1/\eta(G)$, and let $\sigma_1, \sigma_2, \ldots$ be a sequence of G-valued random

variables having the common distribution $\eta/\eta(G)$. Assume all the above objects are independent. Let $T_i = \sum_{j=1}^i S_j$ and $T_0 = 0$. Then g_t can be obtained by solving the SDE

(7)
$$dg_t = \sum_{i=1}^n g_t U_i \circ dw_t^i + g_t U_0 dt$$

for $T_i < t < T_{i+1}$ and letting the process jump at $t = T_i$ according to $g_t = g_{t-}\sigma_i$. For $g \in G$, let $g = g_N^I g_A^I g_K^I$ be the Iwasawa decomposition G = NAK. At the Lie algebra level, for $X \in \mathcal{G}$, let $X = X_N^I + X_A^I + X_K^I$ be the decomposition $\mathcal{G} = \mathcal{N} \oplus \mathcal{A} \oplus \mathcal{K}$. Here, the superscript I indicates that the decomposition is taken with respect to the Iwasawa decomposition.

Let g = nak be the Iwasawa decomposition. Then

$$g\sigma = (na[k\sigma k^{-1}]_N^Ia^{-1})(a[k\sigma k^{-1}]_A^I)([k\sigma k^{-1}]_K^Ik).$$

Hence, $[g\sigma]_A^I = a[k\sigma k^{-1}]_A^I$ and $[g\sigma]_K^I = [k\sigma k^{-1}]_K^I k$. For $U \in \mathcal{G}$ and small s > 0,

$$[ge^{sU}]_A^I \approx a \exp(s[Ad(k)U]_A^I)$$
 and $[ge^{sU}]_K^I \approx \exp(s[Ad(k)U]_K^I)k$.

Hence, if a smooth function f(g) on G depends only on the A-component a of g, then

$$Uf(g) = (d/ds)f(ge^{sU})|_{s=0} = [Ad(k)U]_{\mathcal{A}}^{I}f(a)$$

and

$$UUf(g) = [[Ad(k)U]_{\mathcal{K}}^{I}, Ad(k)U]_{\mathcal{A}}^{I}f(a) + [Ad(k)U]_{\mathcal{A}}^{I}[Ad(k)U]_{\mathcal{A}}^{I}f(a).$$

Let $a_t = \exp(H_t)$. For $a \in A$ with $a = e^H$, define $\log a = H$. Applying (6) with $f(g) = \log(g_A^I) = H$ and noting

$$U_i f(g_{s-}) \circ dw_s^i = U_i f(g_{s-}) dw_s^i + (1/2) U_i U_i f(g_s) ds,$$

we obtain

(8)
$$H_{t} = H_{0} + \int_{0}^{t} \sum_{i=1}^{n} [Ad(k_{s-})U_{i}]_{\mathcal{A}}^{I} dw_{s}^{i} + \int_{0}^{t} \{\frac{1}{2} \sum_{i=1}^{n} [[Ad(k_{s})U_{i}]_{\mathcal{K}}^{I}, Ad(k_{s})U_{i}]_{\mathcal{A}}^{I} + [Ad(k_{s})U_{0}]_{\mathcal{A}}^{I}\} ds + \int_{0}^{t} \int_{G} \log[k_{s-}\sigma k_{s-}^{-1}]_{\mathcal{A}}^{I} N(dsd\sigma).$$

4. Basic Limiting Properties of Lévy Processes

In this section, we will assume that g_t is a Lévy process in G with $g_0 = e$ and μ_t is the distribution of g_t on G.

For probability measures μ on G and ν on a left G-space V, the convolution $\mu * \nu$ is the probability measure on V defined by $\mu * \nu(\Gamma) = \int_{gv \in \Gamma} \mu(dg)\nu(dv)$. We will say that ν is μ -invariant if $\nu = \mu * \nu$. Similarly, if V is a right G-space, we will define $\nu * \mu$ by $\nu * \mu(\Gamma) = \int_{vg \in \Gamma} \nu(dv)\mu(dg)$ and will say that ν is μ -invariant if $\nu = \nu * \mu$.

The measure ν on V will be called a stationary measure (of g_t) if it is μ_t -invariant for all t > 0. If V is a right G-space, vg_t is a Markov process in V starting from $v \in V$. In this case, a stationary measure ν on V can be characterized as a

probability measure such that the Markov process becomes a stationary process if started with ν as initial distribution.

Recall that $\pi: G \to B = G/(N^+AM)$ is the natural projection, and $\pi(N)$ is an open subset of B whose complement has a positive codimension.

As in [5], a probability measure ν on B will be called irreducible if it does not charge $g[\pi(N)]^c$, for any $g \in G$, where the superscript c denotes the complement in B. It is clear that if ν does not charge any submanifold of B of a positive codimension, then it is irreducible.

Let G_{μ} be the smallest closed subgroup of G containing all $\operatorname{supp}(\mu_t)$, t > 0, where $\operatorname{supp}(\mu_t)$ is the support of μ_t . We note that G_{μ} is also the smallest closed subgroup of G containing the support of $\mu = \int_0^{\infty} e^{-t} dt \mu_t$. We will use T_{μ} to denote $\operatorname{supp}(\mu)$. Because the μ_t form a convolution semigroup, we see that T_{μ} is the smallest closed semigroup containing all $\operatorname{supp}(\mu_t)$.

A closed subgroup G' of G will be called totally irreducible if G' is not contained in $\bigcup_{i=1}^r g_i(NN^+AM)^c x$ for some $x, g_1, \ldots, g_r \in G$. We note that if G' is not contained in a finite union of positive codimensional submanifolds of G, then G' is totally irreducible. By Lemme 2.12 in [5], if G_{μ} is totally irreducible, then any stationary measure on B or \tilde{B} is irreducible.

A sequence $g_j \in G$ will be called a contracting sequence if under the Cartan decomposition $g_j = x_j \exp(H_j^+) y_j$, $\alpha(H_j^+) \to \infty$ for any positive root α .

Let $g \in G$ and let λ be a probability measure on B. We define $g\lambda$ to be the probability measure given by $g\lambda(f) = \int f(gb)\lambda(db)$ for $f \in C(B)$ (the space of continuous functions on B).

Theorem 1. Let g_t be a Lévy process in G with $g_0 = e$ and let G_μ and T_μ be defined above. Assume G_μ is totally irreducible and T_μ contains a contracting sequence. Then for any irreducible distribution λ on B, $g_t\lambda$ converges weakly to a point mass δ_z on B as $t \to \infty$, where z is a B-valued random variable.

Consequently, under the Cartan decomposition $g_t = x_t \exp(H_t^+)y_t$, almost surely, as $t \to \infty$, $\alpha(H_t^+) \to \infty$ for any positive root α and $\pi(x_t) \to z$. Moreover, the distribution of z is the unique stationary measure on B.

Proof. As the proof of this theorem is similar to the proof of Théorème 2.6 in [5], we will only outline the main steps.

Let (Ω, P) be the underlying probability space. First assume that λ is a stationary measure on B. Then it is irreducible. As an easy consequence of the stationarity of λ , one can show that, for any $f \in C(B)$, $M_t = g_t \lambda(f) = \int f(g_t b) \lambda(db)$ is a bounded martingale. It follows that for P-almost all $\omega \in \Omega$, $g_t \lambda$ converges weakly to some measure $\zeta(\omega)$ on B as $t \to \infty$ (see the first part of Lemme 2.13 in [5]).

The second step is to show that $\zeta = \delta_z$ for some random point z in B. For random walks, this is done by first showing that for $P \times \mu$ -almost all (ω, ξ) , $g_n(\omega)\xi\lambda \to \zeta(\omega)$ weakly (the second part of Lemme 2.13), and then using this and the existence of a contracting sequence in T_{μ} to show that ζ is a point mass (Lemme 2.14). There is no need to prove this for Lévy processes, as the discrete time result has already established the desired conclusion, i.e., ζ is a point mass δ_z .

To prove $\alpha(H_t^+) \to \infty$ for $\alpha > 0$, it suffices to show that for almost all ω , if g_j is a sequence in G such that $g_j \lambda \to \delta_{z(\omega)}$ weakly, then g_j is contracting. This is a consequence of Lemme 2.11 in [5]. The convergence $\pi(x_t) \to z$ follows from the observation that any limiting point of $\pi(x_t)$ must be the point z above. This shows that the random point z is independent of the choice of the stationary measure λ

on B. By the stationarity of λ , $\lambda = E[g_t\lambda] \to E[\delta_z]$. We see that λ must be equal to the distribution of z. This proves the uniqueness of the stationary measure on B. Now we can see that $x_t \exp(H_t^+)y_t\lambda$ converges weakly to δ_z for any irreducible distribution λ on B.

Remark 1. Recall that in the Cartan decomposition $g_t = x_t \exp(H_t^+)y_t$, the choice for x_t and y_t is not unique. By a suitable choice, we may assume that almost surely, x_t converges to some x_{∞} in K.

The following purely geometric lemma is taken from [5] (see Corollaire (2.4)).

Lemma 1. If g_j is a sequence in G with Cartan decomposition $g_j = x_j \exp(H_j^+)y_j$ and Iwasawa decomposition $g_j = n_j \exp(H_j)k_j$, then the following two statements are equivalent.

- (i) $x_j \to x \in NN^+AM$, and $\alpha(H_i^+) \to \infty$ for $\alpha > 0$.
- (ii) $n_j \to n$ in N, and $\alpha(H_j) \to \infty$ for $\alpha > 0$.

Moreover, the above implies that $\pi(x) = \pi(n)$ and $H_j^+ - H_j$ converges in A.

The limiting properties of g_t under the decomposition G = NAK can be read off immediately from Theorem 1 and Lemma 1.

Corollary 1. Let $g_t = n_t \exp(H_t) k_t$ be the Iwasawa decomposition. Assume the hypotheses of Theorem 1. Then almost surely, as $t \to \infty$, $\alpha(H_t) \to \infty$ for $\alpha > 0$ and $n_t \to n_\infty$ in N with $\pi(n_\infty) = z$.

Now we give some sufficient conditions for the total irreducibility of G_{μ} and the existence of a contracting sequence in T_{μ} required in Theorem 1. The conditions are given in terms of the generator L, so are easy to verify. Recall that L is defined by (4).

As in Section 3, choose U_1, U_2, \ldots, U_n such that $\sum_{i,j=1}^m a_{ij} X_i X_j = \sum_{i=1}^n U_i U_i$. Although such a choice is not unique, the space \mathcal{L} spanned by U_1, U_2, \ldots, U_n is independent of the choice. Let V_1, V_2, \ldots, V_m be an orthonormal basis of \mathcal{G} formed by the eigenvectors of the symmetric matrix $\{a_{ij}\}$ associated to the eigenvalues $\lambda_1, \lambda_2, \ldots, \lambda_m$. Let these eigenvalues be listed so that $\lambda_i > 0$ for $i \leq k$ and $\lambda_i = 0$ for i > k. We have $\sum_{i,j=1}^m a_{ij} X_i X_j = \sum_{i=1}^k \lambda_i V_i V_i$. The space \mathcal{L} is spanned by V_1, \ldots, V_k . We note that if U_1, \ldots, U_n are linearly independent, then k = n.

Let G_L be the closed subgroup of G generated by $\operatorname{supp}(\eta)$ and \mathcal{L} , i.e., G_L is the smallest closed subgroup of G containing $\operatorname{supp}(\eta)$ and all e^{tU} for $U \in \mathcal{L}$ and real t.

Proposition 1. G_L is contained in G_{μ} . Consequently, if $G_L = G$, then $G_{\mu} = G$.

Proof. Let P_t be the semigroup of g_t . For any smooth function f on G with compact support which vanishes near e, we have $(d/dt)P_tf(e)|_{t=0}=Lf(e)=\int_G fd\eta$. This shows that $\operatorname{supp}(\eta)\subset T_\mu\subset G_\mu$.

We now show that $\mathcal{L} \subset \mathcal{G}_{\mu}$, the Lie algebra of G_{μ} . Fix an arbitrary vector U in \mathcal{G} orthogonal to \mathcal{G}_{μ} . It suffices to show that $\langle U, V_i \rangle = 0$ for $i \leq k$.

We have $V_i = \sum_j c_{ij} X_j$ and $\sum_h c_{ih} c_{jh} = \delta_{ij}$. We may choose X_1, X_2, \ldots, X_n such that X_1, \ldots, X_r $(r \leq n)$ span \mathcal{G}_{μ} . Since U is orthogonal to \mathcal{G}_{μ} , $U = \sum_{j>r} c_j X_j$. Let f be a nonnegative smooth function on G which is equal to $(\sum_{j>r} c_j x_j)^2$ near e. By the properties of x_i (see Section 3), we have f(e) = 0, $V_i f(e) = 0$ and $V_i V_i f(e) = 2(\sum_{j>r} c_j c_{ij})^2 = 2\langle U, V_i \rangle^2$. Hence,

$$(d/dt)P_tf(e)|_{t=0} = Lf(e) = \sum_i \lambda_i \langle U, V_i \rangle^2 + \int_G f d\eta.$$

We may choose x_j to vanish on $\exp(\mathcal{G}_{\mu})$ for j > r, so we may also choose f to vanish on $\exp(\mathcal{G}_{\mu})$. Since G_{μ} is closed, it is a topological subgroup of G. We may modify the value of f so that it vanishes outside a small neighborhood of e, hence, vanishes on G_{μ} . Then $P_t f(e) = 0$ for all t. This implies $\langle U, V_i \rangle = 0$ for all i.

For $Y \in \mathcal{P}$, there exist $k \in K$ and $H \in \overline{\mathcal{A}_+}$ such that Y = Ad(k)H. If $H \in \mathcal{A}_+$, then such a Y will be called regular. The regular elements of \mathcal{P} form an open subset of \mathcal{P} whose complement has a positive codimension. For G = SL(n,R), \mathcal{P} is the space of symmetric matrices of trace zero, and $Y \in \mathcal{P}$ is regular if and only if Y has distinct eigenvalues.

Let $Y \in \mathcal{P}$ be regular with Y = Ad(k)H for some $H \in \mathcal{A}_+$, and let $g = e^Y$. Then $g^n = ke^{nH}k^{-1}$, for n = 1, 2, ..., form a contracting sequence. Therefore, if T_{μ} contains some e^Y , where $Y \in \mathcal{P}$ is regular, then T_{μ} contains a contracting sequence. In the proof of Proposition 1, we saw that $\operatorname{supp}(\eta) \subset T_{\mu}$. Hence, if $\operatorname{supp}(\eta)$ contains e^Y for some regular $Y \in \mathcal{P}$, then T_{μ} contains a contracting sequence.

In Section 3, we have seen that if the Lévy measure η is finite, then g_t can be obtained as a solution of the SDE (7) for t < T, where T is an exponential random variable independent of the driving Wiener process w_t . By the support theorem for diffusion processes (see e.g. Theorem 8.1 in Chapter VI of [8]), T_{μ} contains the elements of the form

$$\exp(\sum_{i=1}^{n} c_i U_i + c_0 U_0),$$

where c_1, \ldots, c_n are arbitrary real numbers and c_0 is an arbitrary nonnegative number. Therefore, we have the following conclusion.

Proposition 2. T_{μ} contains a contracting sequence if either of the following two conditions holds.

- (i) $supp(\eta)$ contains e^Y for some regular $Y \in \mathcal{P}$.
- (ii) η is a finite measure and there exist $X \in \mathcal{L}$ and $c \geq 0$ such that $X + cU_0$ is a regular element of \mathcal{P} .

5. The Rate of Convergence

Let g_t be a Lévy process in G, and let $g_t = x_t \exp(H_t^+)y_t$ and $g_t = n_t \exp(H_t)k_t$ be respectively its Cartan and Iwasawa decompositions. Now g_0 is not assumed to be the identity e. The left invariance of g_t implies that $g_t = g_0 g_t^e$, where g_t^e is the Lévy process starting at e. Hence, all the convergences stated in Theorem 1 and Corollary 1 hold also for g_t , except that $\pi(x_t)$ and $\pi(n_t)$ now converge to $g_0 z$ instead of z in B.

In this section we will show that the limit $\tilde{H} = \lim_{t\to\infty} H_t/t$ exists, and we will obtain an integral formula for \tilde{H} . By Lemma 1, \tilde{H} is also the limit of H_t^+/t as $t\to\infty$.

Recall that for $X \in \mathcal{G}$, $X = X_{\mathcal{N}}^I + X_{\mathcal{A}}^I + X_{\mathcal{K}}^I$ is the decomposition $\mathcal{G} = \mathcal{N} + \mathcal{A} + \mathcal{K}$, for $g \in G$, $g = g_N^I g_A^I g_K^I$ is the Iwasawa decomposition G = NAK, and for $a \in A$, $\log a \in \mathcal{A}$ is defined by $a = e^{\log a}$.

For any $g \in G$, the decomposition $g = e^Y k$ with $Y \in \mathcal{P}$ and $k \in K$ is unique. We define $[g]_{\mathcal{P}} = Y$ and let $||Y|| = \langle Y, Y \rangle^{1/2}$. Note that $\log g_A^I$ is not the orthogonal projection of $[g]_{\mathcal{P}}$ to \mathcal{A} in general. However, we have that $||\log[kgk^{-1}]_A^I|| \leq ||[g]_{\mathcal{P}}||$ for $g \in G$ and $k \in K$; see Exercise B.2(iv) in Chapter VI of [6].

Theorem 2. Assume the hypotheses of Theorem 1 and the above notations. Let g_t be a Lévy process in G with generator (5) and a finite Lévy measure η satisfying $\int_G ||[g]_{\mathcal{P}}|| \eta(dg) < \infty$. Then almost surely, as $t \to \infty$, H_t/t converges to some $\tilde{H} \in \mathcal{A}_+$ given by

(9)
$$\tilde{H} = \int_{K} \{ \frac{1}{2} \sum_{i=1}^{n} [[Ad(k)U_{i}]_{\mathcal{K}}^{I}, Ad(k)U_{i}]_{\mathcal{A}}^{I} + [Ad(k)U_{0}]_{\mathcal{A}}^{I} \} \nu(dk) + \int_{K} \int_{G} \log[kgk^{-1}]_{\mathcal{A}}^{I} \eta(dg)\nu(dk),$$

where ν is a stationary measure on K.

Proof. For $g \in G$, let $H(g) \in \mathcal{A}$ be defined by the Iwasawa decomposition $g = ne^{H(g)}k$. Let g_t^e be the Lévy process starting at e. By Théorème 3.5 in [5], if $E[\sup_{k \in K} \|H(kg_t^e)\|] < \infty$, then $(1/i)H(kg_i^e)$ converges to some non-random vector in \mathcal{A}_+ as $i \to \infty$. We note that by (8), the above condition in [5] is implied by our assumption $\int \|[g]_{\mathcal{P}}\|\eta(dg) < \infty$. We need to show that H_t/t converges as $t \to \infty$ along the real axis and the limit \tilde{H} is given by (9). Our proof is independent of the above theorem in [5].

Recall that k_t is a Markov process in K. Suppose the theorem is proved under the additional assumption that the distribution of k_0 is a stationary measure ν on K. Then for ν -almost all $k \in K$, the theorem holds if $k_0 = k$. Since kg_t and g_t have the same (\mathcal{A}_+) -component H_t^+ under the Cartan decomposition for any $k \in K$, we see that the theorem holds regardless of the distribution of k_0 .

Therefore, without loss of generality, we may assume that the distribution of k_0 is ν . In this case, k_t is a stationary process. By the ergodic theory, for any $f \in C(K)$, as $t \to \infty$, $(1/t) \int_0^t f(k_s) ds$ converges almost surely to some random variable X and $E(X) = \int_K f(k) \nu(dk)$.

Let us rewrite (8) as

(10)
$$H_t = H_0 + \mathcal{M}_t + \int_0^t F(k_s)ds + \int_0^t \int_G J(k_{s-}, \sigma)N(dsd\sigma),$$

where $\mathcal{M}_t = \int_0^t \sum_{i=1}^n [Ad(k_{s-})U_i]_A^I dw_s^i$ is a martingale,

$$F(k) = \frac{1}{2} \sum_{i=1}^{n} [[Ad(k)U_i]_{\mathcal{K}}^{I}, Ad(k)U_i]_{\mathcal{A}}^{I} + [Ad(k)U_0]_{\mathcal{A}}^{I} \quad \text{and} \quad J(k,g) = \log[kgk^{-1}]_{\mathcal{A}}^{I}.$$

We note that $||J(k,g)|| \le ||[g]_{\mathcal{P}}||$.

It is easy to see that $\mathcal{M}_t/t \to 0$ as $t \to \infty$. By the ergodic theory mentioned above, $\int_0^t F(k_s) ds/t$ converges almost surely to an \mathcal{A} -valued random variable H' with $E(H') = \int_K F(k) \nu(dk)$.

To show the convergence of $(1/t) \int_0^t \int_G J(k_{s-}, g) N(dsdg)$, let us introduce two discrete time processes, x_n and \bar{x}_n , for $n = 1, 2, 3, \ldots$, defined by

$$x_n = \int_{n-1}^n \int_G J(k_{s-}, g) N(dsdg)$$
 and $\bar{x}_n = \int_{n-1}^n \int_G ||J(k_{s-}, g)|| N(dsdg).$

Both are stationary processes, since k_t is stationary, and $||x_n|| \leq \bar{x}_n$. Note that

$$E(\bar{x}_1) \le E \int_0^1 \int_G \|[g]_{\mathcal{P}} \| N(dsdg) = \int_G \|[g]_{\mathcal{P}} \| \eta(dg) < \infty.$$

It follows, by the law of large numbers, that $\sum_{i=1}^{n} x_i/n$ converges almost surely to some A-valued random variable H^* whose expectation is given by

$$E(H^*) = E(x_1) = E\{\int_0^1 \int_G J(k_s, g) \eta(dg) ds\} = \int_K \int_G J(k, g) \eta(dg) \nu(dk).$$

On the other hand, $\sum_{i=1}^{n} \bar{x}_i/n$ also converges; hence, $\bar{x}_n/n \to 0$. This implies that

$$\sup_{n-1 < t < n} \int_{n-1}^{t} \|J(k_{s-}, g)\| N(dsdg)/n \to 0 \quad \text{ as } n \to \infty.$$

Therefore, $(1/t) \int_0^t \int_G J(k_{s-}, g) N(dsdg) \to H^*$ as $t \to \infty$.

We have proved that as $t \to \infty$, H_t/t converges almost surely to some \mathcal{A} -valued random variable whose expectation is equal to

$$\tilde{H} = \int_K F(k)\nu(dk) + \int_K \int_G J(k,g)\eta(dg)\nu(dk).$$

As this random variable obviously belongs to the σ -field $\mathcal{G}_s = \sigma\{g_s^{-1}g_t; t > s\}$ for any s > 0, and the process g_t has independent increments, by the zero-one law it must be a constant.

In [11], under the additional assumption that $\eta = 0$ and the Haar measure on K is a stationary measure, we derived (9) and used it to obtain an explicit expression for \tilde{H} .

6. Stability of Stochastic Flows: Lyapunov Exponents

Recall that G = NAK is the Iwasawa decomposition. Let Q be a closed subgroup of G containing NA. Via the right action of G on the left coset space $Q \setminus G$, any (left invariant) Lévy process g_t with $g_0 = e$ can be naturally regarded as a stochastic flow on $Q \setminus G$, whose one point motion Qgg_t is a Markov process in $Q \setminus G$ starting from the point Qg. We will use g_t to denote both the Lévy process in G and the induced stochastic flow on $Q \setminus G$.

In general, the local stability of a stochastic flow ϕ_t on a compact manifold S can be described by its Lyapunov exponents, which are defined to be the limit of $(1/t)\log \|D\phi_t(v)\|$ as $t\to\infty$, for some nonzero tangent vector v, where $D\phi_t$ is the differential map of ϕ_t and $\|\cdot\|$ is a metric on S. Under a fairly general condition, it can be shown (see [3]) that the Lyapunov exponents $c_1 > c_2 > \cdots > c_r$ are nonrandom and, for almost all ω and $x \in S$, the associated tangent vectors form a filtration of subspaces of the tangent space T_xS :

$$T_xS = V_1 \supset V_2 \supset \cdots \supset V_r \supset V_{r+1} = \{0\}$$

such that if $v \in V_i - V_{i+1}$, for i = 1, 2, ..., r, then $\lim_{t \to \infty} (1/t) \log ||D\phi_t(v)|| = c_i$. The Lyapunov exponents, which are independent of the metric used above, give the exponential rates at which the length of a tangent vector grows or decays under the flow ϕ_t as $t \to \infty$.

Any point in $Q \setminus G$ can be represented by Qk for some $k \in K$. Fix such a k. Let $kg_t = n_t a_t k_t$ be the Iwasawa decomposition with $a_t = \exp(H_t)$. By the discussion at the beginning of the last section, the convergences stated in Corollary 1 hold for the Iwasawa decompositions of kg_t if the hypotheses of Theorem 1 are satisfied. Moreover, if the integrability assumption in Theorem 2 is also satisfied, then the limit $\tilde{H} = \lim_{t \to \infty} H_t/t$ exists in \mathcal{A}_+ .

Any $Y \in \mathcal{G}$ can be regarded as a tangent vector of $Q \setminus G$ at the point Qe, the tangent vector to the curve $s \mapsto Qe^{sY}$ at s = 0. It is a zero vector if $Y \in Q$, the Lie algebra of Q. Its image Dg(Y) under the differential map of $g \in G$ is the tangent vector to the curve $s \mapsto Qe^{sY}g$ at s = 0.

Because $Q \supset NA$, we have

$$Qe^{Y}kg_{t} = Qa_{t}^{-1}n_{t}^{-1}e^{Y}n_{t}a_{t}k_{t} = Q\exp(Ad(a_{t}^{-1}n_{t}^{-1})Y)k_{t}.$$

Hence, $Dg_t(Dk(Y)) = Dk_t(Ad(a_t^{-1}n_t^{-1})Y)$.

The tangent space of $Q \setminus G$ at Qe can be identified with the orthogonal complement Q' of Q in G. For $X \in G$, we define $||X||_{Q \setminus G}$ to be ||X'||, where X' is the orthogonal projection of X to Q'.

Since K is compact, $Q \setminus G$ possesses a metric invariant under the right action of K. Using this metric and noting that the Lyapunov exponents are independent of the metric, we see that the Lyapunov exponent of the flow g_t corresponding to the vector Dk(Y) is given by

$$\lim_{t \to \infty} (1/t) \log \|Ad(a_t^{-1} n_t^{-1})Y\|_{Q \setminus G}.$$

For any positive root α , let \mathcal{Q}'_{α} be the orthogonal complement of $\mathcal{G}_{\alpha} \cap \mathcal{Q}$ in \mathcal{G}_{α} , and let \mathcal{Q}'_{0} be the orthogonal complement of $\mathcal{M} \cap \mathcal{Q}$ in \mathcal{M} . Then because $NA \subset \mathcal{Q}$,

$$\mathcal{Q}' = \mathcal{Q}'_0 \oplus \sum_{\alpha > 0} \mathcal{Q}'_{\alpha}.$$

Let $X = Ad(n_{\infty}^{-1})Y$ and assume that X is nonzero and is contained \mathcal{Q}'_{α} , where α may be zero. Then for large t,

(11)
$$Ad(a_t^{-1}n_t^{-1})Y = Ad(a_t^{-1})Ad(n_t^{-1})Ad(n_\infty)X = Ad(a_t^{-1})Ad(n_t^{-1}n_\infty)X$$
$$\approx Ad(a_t^{-1})X = Ad(\exp(-H_t))X = \exp(-ad(H_t))X = \exp(-\alpha(H_t))X.$$

The last expression above behaves like $\exp(-\alpha(\tilde{H})t)X$ because $H_t/t \to \tilde{H}$. Since $\|X\|_{Q\setminus G} = \|X\|$, except to justify the above \approx , we see that for a nonzero $Y \in Ad(n_{\infty})Q'_{\alpha}$,

(12)

$$\lim_{t \to \infty} (1/t) \log \|Dg_t(Dk(Y))\| = \lim_{t \to \infty} (1/t) \log \|Ad(a_t^{-1}n_t^{-1})Y\|_{Q \setminus G} = -\alpha(\tilde{H}).$$

Note that $\|\cdot\|$ is used above to denote the metric on $Q\backslash G$.

The \approx in (11) will be justified later. We recall that $n_t a_t k_t$ is the Iwasawa decomposition of kg_t . To emphasize the dependence on k, we will write n_t^k for $n_t = (kg_t)_N^I$.

Theorem 3. Let g_t be a Lévy process in G with $g_0 = e$, considered as a stochastic flow on $Q \setminus G$ via the right action of G. Assume the hypotheses of Theorem 1 and 2, and the notations introduced above. Then the Lyapunov exponents $-\lambda_1 > -\lambda_2 > \cdots > -\lambda_r$ are the distinct values of $-\alpha(\tilde{H})$, where α is any positive root or zero such that $Q'_{\alpha} \neq \{0\}$, and the associated filtration of the tangent space at the point Qk is given by $T_{Qk}(Q \setminus G) = V_1 \supset V_2 \supset \cdots \supset V_r$, where V_i is the direct sum of $Dk(Ad(n_{\infty}^k)Q'_{\alpha})$ for $\alpha(\tilde{H}) \geq \lambda_i$.

We note that all the Lyapunov exponents are nonpositive, and the highest exponent is zero if and only if $\mathcal{Q}'_0 \neq \{0\}$.

7. Proof of Theorem 3

To prove Theorem 3 completely, we need to justify the \approx in (11). We need to show that if α is a root and X is a nonzero root vector of α , $||Ad(a_t^{-1}n_t^{-1}n_\infty)X||_{Q\setminus G}$ has exponential growth rate $-\alpha(\tilde{H})$.

Let $\alpha_1, \ldots, \alpha_m$ be the list of all roots including zero, repeated as many times as their multiplicities, and let X_1, \ldots, X_m be the corresponding root vectors which span \mathcal{G} . We may assume that X_i are orthogonal and each is contained either in \mathcal{Q} or in \mathcal{Q}' . We can write

(13)
$$Ad(n_t^{-1}n_\infty)X_i = \sum_j h_{ij}(t)X_j.$$

We may assume that the roots α_i are ranged in such a way that $\alpha_1(\tilde{H}) \geq \alpha_2(\tilde{H}) \geq \cdots \geq \alpha_m(\tilde{H})$. Since $[\mathcal{G}_{\alpha}, \mathcal{G}_{\beta}] \subset \mathcal{G}_{\alpha+\beta}$, we see that for $n \in N$ and $X \in \mathcal{G}_{\alpha}$, Ad(n)X = X+Y for some $Y \in \sum_{\beta \in \Theta} \mathcal{G}_{\alpha-\beta}$, where Θ is the set of nontrivial linear combinations of positive roots with nonnegative integer coefficients. It follows that $h_{ii}(t) = 1$ and $h_{ij}(t) = 0$ if $\alpha_j \neq \alpha_i - \beta$ for some $\beta \in \Theta$. In particular, $h_{ij}(t) = 0$ if i > j, or if $\alpha_i(\tilde{H}) = \alpha_j(\tilde{H})$ but $i \neq j$.

(14)
$$Ad(a_t^{-1}n_t^{-1}n_\infty)X_i = h_{ii}(t)e^{\alpha_i(-H_t)}X_i + \sum_{j>i}h_{ij}(t)e^{\alpha_j(-H_t)}X_j.$$

Note that the terms on the right hand side of the above are mutually orthogonal and the first term has the desired exponential growth rate $-\alpha_i(\tilde{H})$. In order to prove our claim, it suffices to show that the exponential growth rates of other terms are not greater. In fact, it is enough to show the following weaker statement. For any $\varepsilon > 0$,

(15)
$$|h_{ij}(t)| < e^{-t[\alpha_i(\tilde{H}) - \alpha_j(\tilde{H}) - \varepsilon]} \quad \text{for sufficiently large } t > 0.$$

For $g \in G$, let $\tilde{g} = Ad(g)$: $\mathcal{G} \to \mathcal{G}$ and let $\|\tilde{g}\|$ be the usual operator norm defined by $\|\tilde{g}\| = \sup_{X \in \mathcal{G}, \|X\| = 1} \|\tilde{g}X\|$. Since the inner product $\langle \cdot, \cdot \rangle$ on \mathcal{G} is Ad(K)-invariant, $\|\tilde{k}\| = 1$ for $k \in K$. Using the above X_i as a basis of \mathcal{G} , we may regard \tilde{g} as an m by m matrix. Since G is unimodular, $\det(\tilde{g}) = 1$; hence, $\tilde{G} = \{\tilde{g}; g \in G\}$ is a subgroup of SL(m,R). We note that the matrix norm of \tilde{g} , defined to be the square root of $\sum_{i,j} (\tilde{g}_{ij})^2$, in general is greater than the operator norm $\|\tilde{g}\|$; but the two norms are equivalent.

Consider the process $\tilde{g}_t = Ad(g_t)$, which may be regarded as a (left invariant) Lévy process in \tilde{G} .

Lemma 2. For any t > 0,

We have

$$E[\sup_{0 \le s \le t} \log \|\tilde{g}_s\|] < \infty.$$

The same inequality holds also for \tilde{g}_t^{-1} .

Proof. First assume $\eta=0$. Then \tilde{g}_t can be obtained by solving a SDE of the following form:

(16)
$$d\tilde{g}_t = \sum_{i=1}^m \tilde{g}_t \tilde{X}_i \circ dw_t^i + \tilde{g}_t \tilde{X}_0 dt,$$

where the \tilde{X}_i are some matrices. The coefficients of such an SDE satisfy a global Lipschitz condition; hence, by the method of successive approximation of strong solutions (see, for example, the discussion after Theorem 3.1 in Chapter 4 of [8]), one see that for any t > 0, there exists a constant $C_t > 0$ such that

$$E[\sup_{0 \le s \le t} \|\tilde{g}_s\|^2] \le C_t.$$

The same holds also for \tilde{g}_t^{-1} because \tilde{g}_t^{-1} satisfies an SDE similar to (16) but with $\tilde{g}_t \tilde{X}_i$ replaced by $\tilde{X}_i \tilde{g}_t^{-1}$. This implies the conclusion of Lemma 2 when $\eta = 0$.

Now we consider the general case when η is not assumed to be zero, but is finite and satisfies the integrability condition: $\int_G ||[g]_{\mathcal{P}}|| \eta(dg) < \infty$. Via the map $g \mapsto \tilde{g}$ from $G \to \tilde{G}$, η induces a finite measure $\tilde{\eta}$ on \tilde{G} , which is the Lévy measure of \tilde{g}_t . Since $g = ke^Y$ for some $k \in K$ and $Y \in \mathcal{P}$, and $Y = [g]_{\mathcal{P}}$,

$$\|\tilde{g}\| = \|Ad(e^Y)\| = \|e^{ad(Y)}\| \le e^{c\|Y\|} = \exp(c\|[g]_{\mathcal{P}}\|)$$

for some constant c > 0. We see that $\tilde{\eta}$ satisfies $c_1 = \int \log \|\tilde{g}\| \tilde{\eta}(d\tilde{g}) < \infty$.

Let $\lambda = \tilde{\eta}(\tilde{G})$. By Section 3, there are random times $0 = T_0 < T_1 < T_2 < \cdots$ with independent and exponentially distributed $T_i - T_{i-1}$ of mean λ and independent \tilde{G} -valued random variables $\sigma_1, \sigma_2, \sigma_3, \ldots$ with common distribution $\tilde{\eta}/\lambda$ such that \tilde{g}_t can be obtained by solving the SDE (16) for $T_i < t < T_{i+1}$ and letting it jump at $t = T_i$ according to $\tilde{g}_t = \tilde{g}_{t-1}\sigma_i$. Let A_i be the event that there are i jumps by time t. We have

$$E[\sup_{0 \le s \le t} \log \|\tilde{g}_s\|] = \sum_{i=0}^{\infty} E[\sup_{0 \le s \le t} \log \|\tilde{g}_s\| \mid A_i] P(A_i)$$
$$= \sum_{i=0}^{\infty} E[\sup_{0 \le s \le t} \log \|\tilde{g}_s\| \mid A_i] e^{-\lambda t} (\lambda t)^i / i!.$$

On A_i , $\tilde{g}_s = \tau_1 \sigma_1 \tau_2 \sigma_2 \cdots \tau_j \sigma_j \tau'$ for some $j \leq i$, where τ_k is obtained by solving (16) in (T_{k-1}, T_k) and τ' is obtained by solving (16) in (T_j, s) . Since $E[\|\tau_k\|^2]$ and $E[\|\tau'\|^2]$ have been shown to be bounded by C_t , and $E[\log \|\sigma_k\|] = \int \log \|\tilde{g}\| d\tilde{\eta}/\lambda \leq c_1/\lambda$, we have

$$E[\sup_{0 \le s \le t} \log \|\tilde{g}_s\| \mid A_i] = (i+1)C_t + ic_1/\lambda.$$

Hence, $E[\sup_{0 \le s \le t} \log \|\tilde{g}_s\|] < \infty$. Since $\|[g^{-1}]_{\mathcal{P}}\| = \|[g]_{\mathcal{P}}\|$, the above argument can be easily modified to prove the same conclusion for \tilde{g}_t^{-1} . Lemma 2 is proved. \square

Recall that for $g \in G$, $g = g_N^I g_A^I g_K^I$ is the Iwasawa decomposition G = NAK. For simplicity, we will omit the superscript I in the sequel.

Lemma 3. For any $\varepsilon > 0$, almost surely, $\sup_{k \in K} \|(kg_t^{-1}g_{t+1})_N^{\widetilde{n}}\| \le e^{\varepsilon t}$ for sufficiently large t > 0.

Proof. We note that $g_{t+s} = g_t(g_s' \circ \theta_t)$, where θ_t is the time shift and g_s' is an independent copy of the same Lévy process. Let i be a positive integer. For $i \leq t \leq i+1$, $g_t^{-1}g_{t+1} = (g_{t-i}' \circ \theta_i)^{-1}g_i^{-1}g_{i+1}(g_{t-i}'' \circ \theta_{i+1})$, where g_t' and g_t'' are two independent copies of the same Lévy process. Since $g_i^{-1}g_{i+1}$ is identical in law with

 g_1 , by Lemma 2, we have

$$\begin{split} &E[\sup_{i \leq t \leq i+1} \log \|(g_t^{-1}g_{t+1})\tilde{\ }\|] \\ \leq &E[\sup_{0 \leq s \leq 1} \log \|(g_s'^{-1})\tilde{\ }\|] + E[\log \|(g_i^{-1}g_{i+1})\tilde{\ }\|] + E[\sup_{0 \leq s \leq 1} \log \|(g_s'')\tilde{\ }\|] < \infty. \end{split}$$

For $g \in G$ and $k \in K$, $kg = (kg)_N(kg)_A k'$ for some $k' \in K$ and $(kg)_N = kgk'^{-1}(kg)_A^{-1}$. For $a \in A$, \tilde{a} is a diagonal matrix such that the product of its diagonal entries is equal to one. This implies that $\|\tilde{a}^{-1}\| \leq \|\tilde{a}\|^{m-1}$. On the other hand, from $(kg)_N(kg)_A = kgk'^{-1}$ and the fact that $(kg)_A^{\tilde{a}}$ and $(kg)_N^{\tilde{a}}(kg)_A^{\tilde{a}}$ have the same diagonal, we see that $\|(kg)_A^{\tilde{a}}\| \leq \|\tilde{g}\|$. Therefore,

$$||(kg)\tilde{N}|| \le ||\tilde{g}|| \cdot ||[(kg)\tilde{A}]^{-1}|| \le ||\tilde{g}||^m.$$

We have

$$E[\sup_{i \le t \le i+1} \sup_{k \in K} \log \|(kg_t^{-1}g_{t+1})_{\tilde{N}}\|] \le mE[\sup_{i \le t \le i+1} \log \|(g_t^{-1}g_{t+1})^{\tilde{}}\|] < \infty.$$

For $i=1,2,3,\ldots,u_i=\sup_{i\leq t\leq i+1}\sup_{k\in K}\log\|(kg_t^{-1}g_{t+1})_N^{\tilde{n}}\|$ are iid random variables with finite expectation. As a consequence of the strong law of large numbers, $(1/i)u_i\to 0$ as $i\to\infty$. This implies the conclusion of Lemma 3.

The following lemma establishes (15) and, hence, completes the proof of Theorem 3. It has been pointed out by the anonymous referee that an inequality of similar nature for discrete times appears in Raghunathan's proof of the Oseledec ergodic theorem (Israel Journal of Math. 32, 356-362, 1979; MR 81f:60016).

Lemma 4. For $h_{ij}(t)$ defined in (13), we have, for any $\varepsilon > 0$, almost surely,

$$|h_{ij}(t)| \le \exp\{-t[\alpha_i(\tilde{H}) - \alpha_i(\tilde{H}) - \varepsilon]\}$$

for sufficiently large t > 0.

Proof. Fix an arbitrarily small $\delta > 0$. Let $g_t = n_t a_t k_t$ be the Iwasawa decomposition. Then $g_t^{-1} g_{t+1} = k_t^{-1} a_t^{-1} n_t^{-1} n_{t+1} a_{t+1} k_{t+1}$ and

$$k_t g_t^{-1} g_{t+1} = (a_t^{-1} n_t^{-1} n_{t+1} a_t) a_t^{-1} a_{t+1} k_{t+1}.$$

It follows that $n_t^{-1}n_{t+1} = a_t(k_tg_t^{-1}g_{t+1})_Na_t^{-1}$. We will write $\tilde{n}(t)$ for $(k_tg_t^{-1}g_{t+1})_{\tilde{N}}$. Let $\tilde{n}(t)X_i = \sum_i c_{ij}(t)X_j$. Then

$$Ad(n_t^{-1}n_{t+1})X_i = \tilde{a}_t \tilde{n}(t)\tilde{a}_t^{-1}X_i = e^{-\alpha_i(H_t)}\tilde{a}_t \tilde{n}(t)X_i = \sum_j e^{-(\alpha_i - \alpha_j)(H_t)}c_{ij}(t)X_j.$$

The coefficients $c_{ij}(t)$ have properties similar to those stated for $h_{ij}(t)$ after (13). In particular, $c_{ij}(t) = 0$ if $i \neq j$ and $\alpha_j \neq \alpha_i - \beta$ for some $\beta \in \Theta$.

By Lemma 3, the norm of the matrix $\{c_{ij}(t)\}\$ is $\leq e^{c\delta t/2}$ for sufficiently large t>0, where $c=\min\{(\alpha_i-\alpha_j)(\tilde{H}); (\alpha_i-\alpha_j)(\tilde{H})>0\}$. Since $H_t/t\to \tilde{H}$ as $t\to\infty$, we have

$$e^{-(\alpha_i - \alpha_j)(H_t)}c_{ij}(t) = e^{-t(1-\delta)(\alpha_i - \alpha_j)(\tilde{H})}b_{ij}(t),$$

where the matrix $\{b_{ij}(t)\}$ has norm ≤ 1 for sufficiently large t > 0.

We have
$$Ad(n_t^{-1}n_{\infty})X_i = \lim_{k \to \infty} Ad(n_t^{-1}n_{t+1}n_{t+1}^{-1}n_{t+2} \cdots n_{t+k}^{-1}n_{t+k+1})X_i$$
 and
$$Ad(n_t^{-1}n_{t+1}n_{t+1}^{-1}n_{t+2} \cdots n_{t+k}^{-1}n_{t+k+1})X_i$$

$$= Ad(n_t^{-1}n_{t+1})Ad(n_{t+1}^{-1}n_{t+2}) \cdots Ad(n_{t+k}^{-1}n_{t+k+1})X_i$$

$$= \sum_{j_1, \dots, j_k, j} e^{-(t+k)(1-\delta)(\alpha_i - \alpha_{j_1})(\tilde{H})} b_{ij_1}(t+k)$$

$$\times e^{-(t+k-1)(1-\delta)(\alpha_{j_1} - \alpha_{j_2})(\tilde{H})} b_{j_1j_2}(t+k-1) \cdots$$

$$\cdots e^{-(t+1)(1-\delta)(\alpha_{j_{k-1}} - \alpha_{j_k})(\tilde{H})} b_{j_{k-1}j_k}(t+1) e^{-t(1-\delta)(\alpha_{j_k} - \alpha_{j})(\tilde{H})} b_{j_kj}(t)X_j$$

$$= \sum_j e^{-t(1-\delta)(\alpha_i - \alpha_j)(\tilde{H})} C_{ij}(t,k)X_j,$$

where $C_{ij}(t,k)$ is given by

$$\sum_{j_1,\dots,j_k} e^{-k(1-\delta)(\alpha_i - \alpha_{j_1})(\tilde{H})} b_{ij_1}(t+k) e^{-(k-1)(1-\delta)(\alpha_{j_1} - \alpha_{j_2})(\tilde{H})} b_{j_1j_2}(t+k-1) \cdots$$

$$\cdots e^{-(1-\delta)(\alpha_{j_{k-1}}-\alpha_{j_k})(\tilde{H})}b_{j_{k-1}j_k}(t+1)b_{j_kj}(t).$$

The matrix $\{C_{ij}(t,k)\}$ has norm ≤ 1 . Since $Ad(n_t^{-1}n_\infty)X_i = \sum_j h_{ij}(t)X_j$, the above shows that

$$h_{ij}(t) = e^{-t(1-\delta)(\alpha_i - \alpha_j)(\tilde{H})} \lim_{k \to \infty} C_{ij}(t, k).$$

Lemma 4 is proved by letting $\varepsilon = \delta \max_{j>i} (\alpha_i - \alpha_j)(\tilde{H})$.

8. Global Stability

Let g_t be a Lévy process in G with $g_0 = e$ satisfying the hypotheses stated in Theorems 1 and 2, and let $g_t = x_t \exp(H_t^+)y_t$ be the Cartan decomposition. We know that $H_t^+/t \to \tilde{H} \in \mathcal{A}_+$ and we may assume $x_t \to x_\infty$ in K as $t \to \infty$. Because of the non-uniqueness of (x,y) in the Cartan decomposition $g = x \exp(H^+)y$, we have non-unique choices for x_t , hence, also for x_∞ . But all possible choices for x_∞ are given by $x_\infty m$ for $m \in M$.

As before, let Q be a closed subgroup of G containing NA, and consider g_t as a stochastic flow on $Q \setminus G$ via the right action. We can show that almost surely there is an open subset of $Q \setminus G$ with a positive-codimensional complement, which in fact is the image of a fixed subset of $Q \setminus G$ under a random "rotation", such that each component of this open set is shrunk to a "moving" positive codimensional limiting set exponentially by g_t as $t \to \infty$. In the case of $Q \supset NAM_0$, where M_0 is the identity component of M, each limiting set is a single point. We note that in this case, all the Lyapunov exponents are strictly negative.

If Q = NAM, then $Q \setminus G$ is B, introduced in Section 2. We will first establish the result for g_t on \tilde{B} , from which the result for g_t on more general spaces can be read off.

Recall that $\tilde{\pi}$: $G \to \tilde{B}$ is the natural projection. By the Bruhat decomposition of G discussed in Section 2, $\Lambda = \tilde{\pi}(NAMN^+)$ is a connected open subset of \tilde{B} with a positive-codimensional complement. Let o be the coset (NAM). Then we may write $\Lambda = oN^+$ via the right action of G on \tilde{B} .

It is clear that the action of $a \in A$ fixes the point o. Since $a^{-1}n'a \in N^+$ for $a \in A$ and $n' \in N^+$, we see that a leaves Λ invariant. Let $a = \exp(H_t^+)$, and

 $n' = e^Y$ for some root vector Y of a positive root α . Then

$$oe^{Y}a = o\exp(Ad(a^{-1})Y) = o\exp(e^{ad(-H_{t}^{+})}Y) = o\exp(e^{-\alpha(H_{t}^{+})}Y).$$

Since $H_t^+/t \to \tilde{H}$, we see that the distance between $on' \exp(H_t^+)$ and o tends to zero at a negative exponential rate $-\alpha(\tilde{H})$ as $t \to \infty$.

Now let $\Lambda(\omega) = \Lambda x_{\infty}(\omega)^{-1}$, where ω is a fixed typical sample path. We have mentioned before that the choice for x_{∞} is not unique. However, two different choices for x_{∞} differ only by a factor $m \in M$ on the right; this amounts to replacing x_{∞}^{-1} above by mx_{∞}^{-1} for some $m \in M$. Since $\Lambda m = \Lambda$, we see that the definition of $\Lambda(\omega)$ is independent of the choice of x_{∞} .

Any $z \in \Lambda(\omega)$ can be expressed as $z = on'x_{\infty}^{-1}$ for some $n' \in N^+$. We have suppressed ω for simplicity:

$$zg_t = on'x_{\infty}^{-1}x_t \exp(H_t^+)y_t \approx on' \exp(H_t^+)y_t$$

for large t > 0. The above \approx can be easily justified. Since K is compact, we may assume that the right action of K leaves the distance on \tilde{B} invariant. It follows that the distance between zg_t and oy_t tends to zero at a negative exponential rate $\leq -\inf_{\alpha>0} \alpha(\tilde{H})$. To summarize, we have

Theorem 4. Let g_t be a Lévy process in G satisfying the hypotheses of Theorems 1 and 2 with $g_0 = e$, and let $g_t = x_t \exp(H_t^+)y_t$ be its Cartan decomposition. Consider g_t as a stochastic flow on $\tilde{B} = (NAM)\backslash G$ via the right action of G on \tilde{B} . The set $\Lambda = oN^+$ is a connected open subset of \tilde{B} with a positive-codimensional complement. For almost all ω , all the points in $\Lambda x_{\infty}(\omega)^{-1}$ will converge to the "moving" point $oy_t(\omega)$ exponentially under the flow g_t in the sense that

(17)
$$\forall z \in \Lambda x_{\infty}^{-1}, \quad \limsup_{t \to \infty} \frac{1}{t} \log \operatorname{dist}(zg_t, oy_t) \le -\lambda,$$

where $-\lambda$ is the highest Lyapunov exponent of g_t on \tilde{B} .

Now consider g_t as a stochastic flow on $B_0 = (NAM_0)\backslash G$. This is a covering space of $(MAN)\backslash G$ with the covering map given by $p: (M_0AN)g \mapsto (MAN)g$. Then $\Lambda_0 = p^{-1}(\Lambda)$ is an open subset of $(M_0AN)\backslash G$ with a positive-codimensional complement. Let u be the point in $(NAM_0)\backslash G$ represented by the coset (NAM_0) . Then the connected components of Λ_0 are given by umN^+ for $m \in M$, and each of those is mapped diffeomorphically onto Λ by p. Therefore, under the stochastic flow g_t , all the points in $umN^+x_0^{-1}$ will converge to umy_t exponentially. We note that $umN^+ = um'N^+$ if and only if $m' \in M_0m$.

Now let Q be a closed subgroup of G containing NAM_0 , let p_Q be the natural map: $(M_0AN)\backslash G \to Q\backslash G$ defined by $(M_0AN)g \mapsto Qg$, and let $\Lambda_Q = p_Q(\Lambda_0)$. The connected components of Λ_Q are given by $p_Q(umN^+)$ for $m \in M$. We note that even if $umN^+ \neq um'N^+$, $p_Q(umN^+)$ and $p_Q(um'N^+)$ may still be the same.

Corollary 2. Assume Q is a closed subgroup of G containing NAM_0 . Then Λ_Q defined above is an open subset of $Q\backslash G$ with a positive-codimensional complement. Under the stochastic flow g_t , almost surely, all the points in each component of $\Lambda_Q x_{\infty}^{-1}$ will converge to a single "moving" point exponentially in the sense of (17), where Λ and oy_t should be replaced, respectively, by Λ_Q and $p_Q(um)y_t$, and $-\lambda$ is the highest Lyapunov exponent of g_t on $Q\backslash G$.

To illustrate the structures mentioned above, let G = SL(n,R). Then $M_0 = \{e\}$, and $\tilde{B}_0 = (NA)\backslash G$ can be identified with K = SO(n). The right action of G on K is given by hg = k for $h \in K$ and $g \in G$ with Iwasawa decomposition hg = nak. The row vectors of k are obtained from the row vectors of the matrix product $h \cdot g$ by a Gram-Schmidt orthogonalization. For $\gamma \subset \{1, 2, \ldots, n\}$ and a matrix $g \in G$, let $g[\gamma]$ be the determinant of the submatrix of g formed by the rows and columns indexed by g. We have g0 for g1 for g2 for g3 for g4 for g5 for g6 for g8. Each connected component of g9 consists of g9 for all g9. In particular, g9 for all g9 for all g9.

Remark 2. We now consider the general case of the stochastic flow g_t on $Q \setminus G$ with $Q \supset NA$. If $Q \not\supset M$, there exists a zero Lyapunov exponent and we cannot expect the clustering around single points. However, our proof shows that there is an open subset of $Q \setminus G$ with a positive-codimensional complement such that each of its connected component is shrunk to a lower dimensional "moving" set exponentially by g_t .

For example, in the case of Q=NA, let $p'\colon G\to (NA)\backslash G$ be the natural projection and let $\Lambda'=p'(MN^+)$. Then Λ' is an open subset of $(NA)\backslash G$ with a positive-codimensional complement. For almost all ω , g_t shrinks $\Lambda'x_\infty(\omega)^{-1}$ exponentially into the lower-dimensional "moving" set $p'(M)y_t$ as $t\to\infty$ in the sense that the distance between any point in $\Lambda'x_\infty(\omega)^{-1}$ and the set $p'(M)y_t$ tends to zero at an exponential rate $\leq -\lambda$, where $-\lambda$ is the highest negative Lyapunov exponent of g_t on $(NA)\backslash G$.

9. Some Stochastic Flows on Spheres

In this section, we will consider some examples of stochastic flows on the (n-1)-dimensional sphere S^{n-1} , embedded as the unit sphere in \mathbb{R}^n .

We will first make some general remarks about continuous Lévy processes in G and the induced stochastic flow on a manifold S via the right action of G on S. Such a process can be obtained as the solution of the following SDE on G:

$$dg_t = \sum_{i=1}^n g_t U_i \circ dw_t^i + g_t U_0 dt,$$

where $U_0, U_1, \ldots, U_n \in \mathcal{G}$ and $w_t = \{w_t^i\}$ is an *n*-dimensional Wiener process. By Propositions 1 and 2, the hypotheses of Theorem 1 are satisfied if U_1, \ldots, U_n generate \mathcal{G} and their linear span contains a regular element of \mathcal{P} . We note that the integrability assumption in Theorem 2 is always satisfied for a continuous Lévy process.

Any $U \in \mathcal{G}$ induces a vector field U^* on S defined by $U^*f(x) = (d/ds)f(xe^{sU})|_{s=0}$ for smooth functions f on S and $x \in S$. The stochastic flow g_t on S is the solution flow of the following SDE on S:

$$dx_t = \sum_{i=1}^m U_i^*(x_t) \circ dw_t^i + U_0^*(x_t)dt.$$

Stochastic Flows in SL(n,R). Let G = SL(n,R). Consider its right action on S^{n-1} defined by $x \mapsto xg = (x \cdot g)/\|x \cdot g\|$ for $x = (x_1, x_2, \dots, x_n) \in S^{n-1}$ and $g \in G$. Here x is considered as a row vector, the dot \cdot denotes the usual matrix multiplication, and $\|\cdot\|$ is the Euclidean norm on R^n . Thus, any Lévy process g_t

in G can be regarded as a stochastic flow on S^{n-1} via this right action. We will assume that g_t satisfies the hypotheses of Theorems 1 and 2.

Let $v=(1,0,\cdots,0)$ and $Q=\{g\in G;\ vg=v\}$. Then $S^{n-1}=Q\backslash G$. It is easy to see that Q consists of all matrices in G whose first rows have the form $(a,0,\cdots,0)$ for some a>0. The root structure of G=SL(n,R) has been described in Section 2. We note that M is a discrete group, so $\mathcal{M}=\{0\}$. By Theorem 3, the stochastic flow has n-1 negative Lyapunov exponents: $-\lambda_1>-\lambda_2>\cdots>-\lambda_{n-1}$. Furthermore, using the right action of N^+ on S^{n-1} , we can see that the set Λ_Q in Corollary 2 has two components: $S_1=\{x=(x_1,\ldots,x_n)\in S;\ x_1>0\}$ and $S_2=\{x=(x_1,\ldots,x_n)\in S;\ x_1<0\}$; and the points $p_Q(um)$ for S_1 and S_2 are, respectively, v and -v. We can draw the following conclusions: For almost all ω , there is a great hypercircle C_ω on S^{n-1} such that for any two points z_1 and z_2 ,

(i) if z_1 and z_2 lie on the same side of C_{ω} , then

(18)
$$\limsup_{t \to \infty} (1/t) \log \operatorname{dist}(z_1 g_t, z_2 g_t) \le -\lambda_1;$$

(ii) if z_1 and z_2 lie on the different sides of C_{ω} , then $\operatorname{dist}(z_1g_t, z_2g_t) \to 1$ (diameter of S^{n-1}) as $t \to \infty$, where dist is the distance on S^{n-1} induced by the Euclidean distance

We note that the above conclusions hold for any stochastic flow on S^{n-1} as long as it is induced by a Lévy process in SL(n,R) which satisfies the hypotheses of Theorems 1 and 2.

Sometimes it is more convenient to work with a Lévy process g_t in GL(n,R), the group of n by n nonsingular real matrices, rather than a process in its subgroup SL(n,R). The action of GL(n,R) on S^{n-1} is defined exactly as for SL(n,R). Although GL(n,R) is not semisimple, it is a direct product of R_+ (the multiplication group of positive reals) and SL(n,R), via the group isomorphism $g \mapsto (\det(g), \det(g)^{-1/n}g)$ from GL(n,R) onto $R_+ \times SL(n,R)$. As the action of R_+ on S^{n-1} is trivial, we may assume that g_t is a Lévy process in SL(n,R); hence, the above conclusions hold.

We now consider such an example. Let E_{ij} be the n by n matrix which has 1 at place (i,j) and 0 elsewhere. Such matrices form a basis of the Lie algebra of GL(n,R). Consider the following SDE on GL(n,R):

$$dg_t = \sum_{i,j=1}^n c_{ij} g_t E_{ij} \circ dw_t^{ij},$$

where $w_t = \{w_t^{ij}\}$ is an n^2 -dimensional Wiener process and the c_{ij} are constants. The solution g_t of this SDE with $g_0 = I_n$ (the n by n identity matrix) is a continuous Lévy process in GL(n, R). The hypotheses are satisfied if all the c_{ij} are nonzero.

For
$$x = (x_1, \dots, x_n) \in S^{n-1}$$
,

$$x \cdot \exp(sE_{ij}) = x \cdot (I + sE_{ij}) + O(s^2) = (x_1, \dots, x_j + sx_i, \dots, x_n) + O(s^2)$$

and its norm = $1 + sx_ix_j + O(s^2)$. From this, we can show that the induced vector field E_{ij}^* on S^{n-1} is given by

$$E_{ij}^*(x) = x_i(\partial/\partial x_j) - x_i x_j \nabla,$$

where $\nabla = \sum_{i=1}^{n} x_i (\partial/\partial x_i)$. This is the orthogonal projection to S^{n-1} of the vector field $x_i (\partial/\partial x_j)$ on \mathbb{R}^n . The stochastic flow g_t is the solution flow of the following

SDE on S^{n-1} :

$$dx_t = \sum_{i,j=1}^{n} c_{ij} E_{ij}^*(x_t) \circ dw_t^{ij}.$$

If all $c_{ij} = 1$, then the one point motion of the stochastic flow is Brownian motion in S^{n-1} (see [10]).

Stochastic Flows in the Lorentz Group. The Lorentz group on R^{n+1} is the group of linear transformations, or (n+1) by (n+1) real matrices, which leave the quadratic form $x_0^2 - \sum_{i=1}^n x_i^2$ invariant. We will use x_0, x_1, \ldots, x_n as Cartesian coordiates on R^{n+1} , and $x = (x_1, \ldots, x_n)$ as coordinates on the subspace R^n which contains S^{n-1} as the unit sphere. The Lorentz group has four connected components. Let $G = SO_+(1, n)$ be the identity component.

We now define a right action of G on S^{n-1} . For $x \in S^{n-1}$ and $g \in G$, let $(v,y)=(1,x)\cdot g$, where v is a real number, $y \in R^n$ and the dot \cdot denotes the matrix multiplication. Then $v^2 - ||y||^2 = 1 - ||x||^2 = 0$, and hence, $y/v \in S^{n-1}$. We define xg = y/v. This is a well defined right action of G on S^{n-1} . Via this action, any Lévy process in $G = SO_+(1,n)$ can be regarded as a stochastic flow on S^{n-1} .

The Lie algebra \mathcal{G} of G is the space of the matrices having the following block form:

$$\left[\begin{array}{cc} 0 & y \\ y^* & B \end{array}\right],$$

where $B \in o(n)$ (the space of n by n skew-symmetric matrices), $y = (y_1, \ldots, y_n)$ is a row vector and y^* is the transpose of y. For $\theta \in S^{n-1}$, let X_{θ} be such a matrix with B = 0 and $y = \theta$. We may take K to be the compact subgroup of matrices

$$\begin{bmatrix} 1 & 0 \\ 0 & B \end{bmatrix},$$

with $B \in SO(n)$. Then \mathcal{P} is spanned by X_{θ} , $\theta \in S^{n-1}$. All the maximal abelian subspaces of \mathcal{P} are one dimensional. Fix a $\theta \in S^{n-1}$. We may take \mathcal{A} to be such a subspace spanned by X_{θ} , and \mathcal{A}_+ to be the half line $\{cX_{\theta}; c > 0\}$. There are only two roots $\pm \alpha$, given by $\alpha(X_{\theta}) = 1$.

Let $Q = \{g \in G; \theta g = \theta\}$. Then $S^{n-1} = Q \setminus G$. We can show that M is the group of orthogonal transformations on R^n which fix the point θ and Q = NAM. We may take θ to be the point o in Section 8. Since $\Lambda = oN^+$ is a simply connected open subset of S^{n-1} with a positive-codimensional complement and it is invariant under the action of M, the complement of Λ has to be the point antipodal to θ . Therefore, by Theorems 3 and 4, for any stochastic flow g_t on S^{n-1} induced by a Lévy process in $SO_+(1,n)$ which satisfies the hypotheses of Theorems 1 and 2, there is only one negative exponent $-\lambda$ and, for almost all ω , there is a random point $x(\omega)$ on S^{n-1} such that its complement is shrunk by the stochastic flow exponentially in the sense of (18), where z_1 and z_2 are any two points on S^{n-1} distinct from $x(\omega)$, and $-\lambda_1 = -\lambda$.

Let X_i be X_{θ} , where $\theta = \theta_i$ is the vector having 1 in the *i*-th place and zero elsewhere. Consider the following SDE on $SO_+(1, n)$:

$$dg_t = \sum_{i=1}^n c_i g_t X_i \circ dw_t^i.$$

Its solution is a Lévy process satisfying the hypotheses if all constants c_i are nonzero. Since $(1, x) \cdot \exp(sX_i) = (1, x) \cdot (I_{n+1} + sX_i) + O(s^2) = (1 + sx_i, x + s\theta_i) + O(s^2)$, one can show that the induced vector field X_i^* on S^{n-1} is given by $X_i^*(x) = (\partial/\partial x_i) - x_i \nabla$, which is the orthogonal projection to S^{n-1} of the coordinate vector field $(\partial/\partial x_i)$ on R^n . Hence, g_t is the stochastic flow mentioned at the beginning of the paper.

Finally, we will look at a simple example of a discontinuous stochastic flow. First note that the SDE $dg_t = g_t X_1 \circ dw_t$, where w_t is a one dimensional Wiener process, defines a Lévy process g_t in $G = SO_+(1,n)$. It is the solution flow of the SDE $dx_t = X_1^*(x_t) \circ dw_t$ on S^{n-1} and does not satisfy the hypotheses of Theorem 1. For $x \in S^{n-1}$, let ϕ be the angle between x and $\theta = (1,0,\ldots,0)$. Then the above SDE on S^{n-1} can be written as

$$d\phi_t = \sin(\phi_t) \circ dw_t$$
.

The solution is given by $\phi_t = F^{-1}(F(\phi_0)e^{-W_t})$, where $F(\phi) = \log(\csc \phi + \cot \phi)$. We see that the stochastic flow g_t is recurrent. In particular, under the flow, the distance between any two points will return to the original value infinitely often.

Now we add random rotations to g_t at exponentially spaced random times. Let η be the distribution of each random rotation and assume that η is finite, $\eta(\{e\}) = 0$ and $\text{supp}(\eta) = K = SO(n)$. By the discussion in Section 3, the resulting Lévy process in G has generator

$$Lf(g) = (1/2)X_1X_1f(g) + \int_K [f(g\tau) - f(g)]\eta(d\tau).$$

This process satisfies the hypotheses of Theorems 1 and 2. Therefore, as a stochastic flow on S^{n-1} , it will shrink the complement of a random point exponentially to a single point. This is a little surprising—as rotations leave distance invariant, it would have seemed that after rotations the distance between points should still remain recurrent.

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